

# **CAN** bus protection



# Is this presentation suited for you?

#### Where do you stand with CAN bus protection?

### Beginner?

I am not familiar with this subject. I am in the discovery phase and would like an overview and a basic understanding of the technology.

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Overview

#### **Intermediate?**

I have a basic understanding of this subject. I would like to go deeper in details and tackle more aspects of this subject.

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#### Basic

#### Advanced?

I am very familiar with this subject. I would like to deepen my knowledge and become an expert.

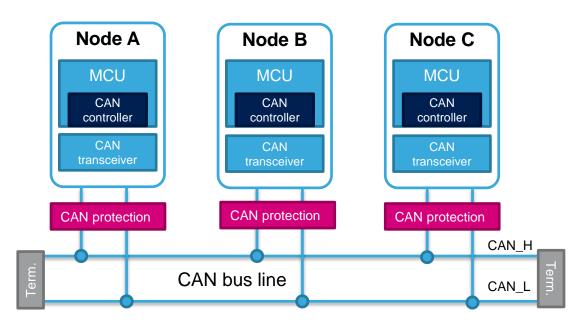
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In depth



## Basics on CAN bus

- CAN stands for Controller Area Network
- It is very popular in the automotive industry
- It is a serial bi-directional half-duplex multi-master communication bus
- 2 lines:
  - CAN H (CAN High)
  - CAN\_L (CAN Low)
- 2 standards:
  - Low-speed, fault-tolerant
  - High-speed



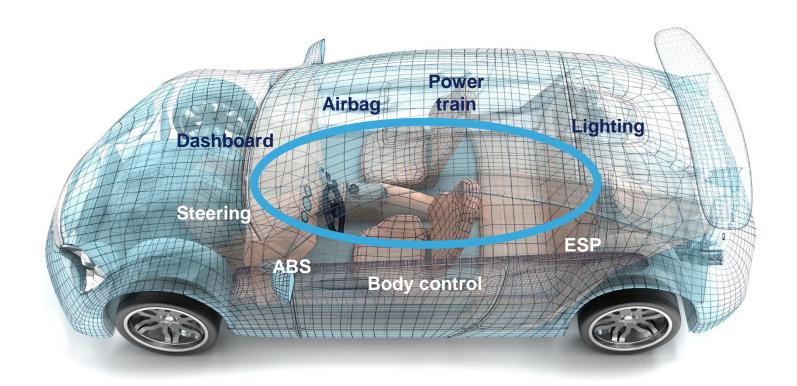
### **Benefits of CAN**

- Cost-effective
- Light-weight
- Reliable / transmission safety
- Information available for all nodes



## Where is CAN 4

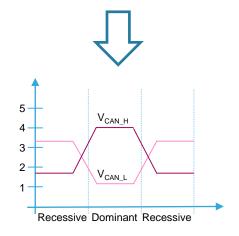
 As the CAN bus is reliable, it is used to connect together most of the modules in the car, including safety and critical functions

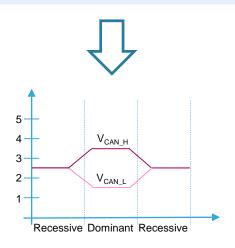




## Basics on CAN bus

Parameters	High-speed CAN	Low-speed CAN
Physical layer standards	ISO 11898-2	ISO 11898-3
Data rate	Up to 1 Mbit/s	Up to 125 kbit/s
Maximum length	30 m	500 m
Termination	120 Ω shunt	$2.2~k\Omega$ serial on each line
Recessive voltage level	$V_{CAN\_H} = 1.75 \text{ V} $ $V_{CAN\_L} = 3.25 \text{ V}$	$V_{CAN\_H} = V_{CAN\_L} = 2.5 \text{ V}$
Dominant voltage level	$V_{CAN\_H} = 4 V$ $V_{CAN\_L} = 1 V$	$V_{CAN\_H} - V_{CAN\_L} = 2 V$







# Why protection is needed?

- Automotive systems require a high level of robustness and must be 100% reliable when they control safety devices.
- The automotive industry has defined standards to guarantee the robustness of car embedded electronics.



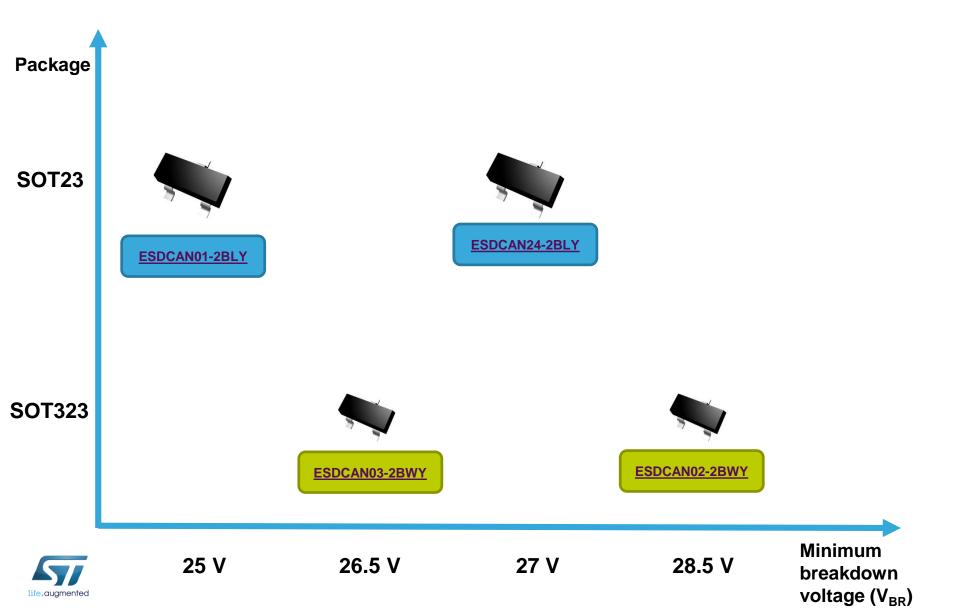
# Why protection is needed?

### CAN protection must comply with the following main standards

Hazards	Туре	Standards
ESD protection	Voltage spikes due to electro-static discharges.	ISO 10605
Surge protection	Voltage spikes due to switching processes (influenced by capacitance and inductances of the wiring harness)	ISO 7637-3 pulse 3a/3b
Jump start	Application of 24 V on all inputs to simulate a jump start with a 24 V battery	ISO 16750
Reverse battery	Application of -28 V (during 60 s) to simulate a reversed battery connection in case of using an auxiliary starting device	ISO 16750



# CAN protection portfolio



## ESDCAN series versus standards

Hazards	Standards	ESDCAN24-2BLY	ESDCAN01-2BLY	ESDCAN02-2BWY	ESDCAN03-2BWY
ESD protection	ISO 10605	+30 kV contact	+30 kV contact	+30 kV contact	+30 kV contact
Surge protection	ISO 7637-3 pulse 3a/3b	<b>✓</b>	<b>✓</b>	<b>✓</b>	
Jump start	ISO 16750	V <sub>BR</sub> min (reverse) = 27 V	V <sub>BR</sub> min (reverse) = 25 V	V <sub>BR</sub> in (reverse) = 28.5 V	V <sub>BR</sub> in (reverse) = 26.5 V
Reverse battery	ISO 16750	V <sub>BR</sub> min (forward) = 27 V	V <sub>BR</sub> min (forward) = 25 V	V <sub>BR</sub> min (forward) = 28.5 V	V <sub>BR</sub> min (forward) = 26.5 V



# ESDCAN series: quality of protection 10

- Not only protection features must comply with standards, but they must efficiently protect against surges.
- The quality of protection features is measured by its ability to clamp overvoltages and overcurrent, thus protect the IC (CAN controller) against EOS / ESD
- The lower the clamping voltage, the greater the circuit's better ESD. immunity.



# Let's go further

In-depth information Protection of automotive electronics - guidelines for design and component selection Application note AN2689

Pspice models

Selection & sampling

Our **product selector**: Automotive dataline ESD protection

Our **selection guide**: Automotive-grade protection devices and rectifiers (.pdf)

